

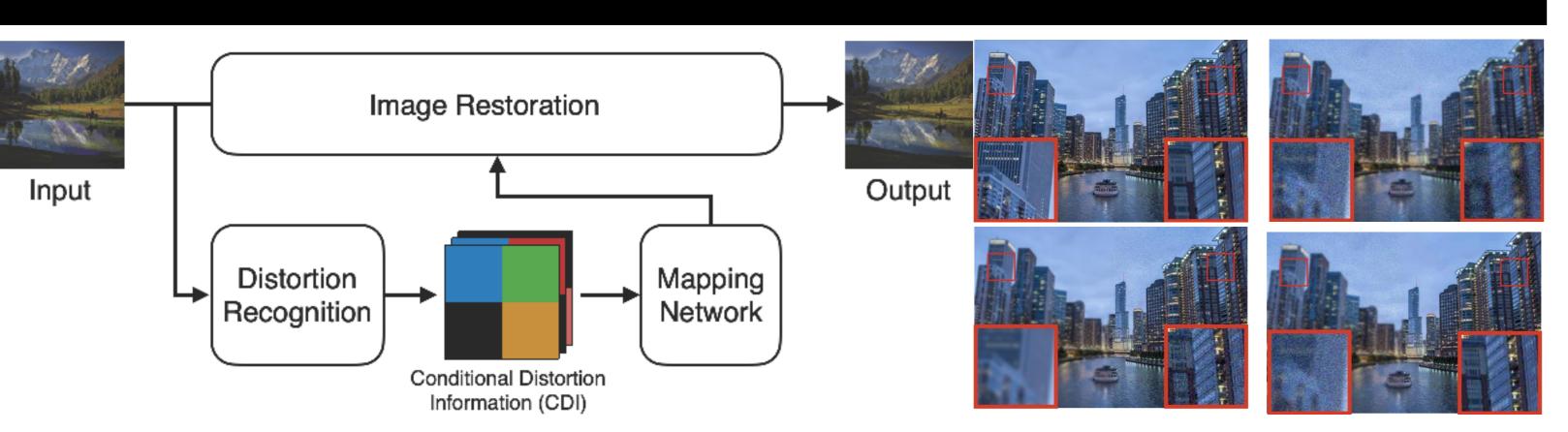
Exploiting Distortion Information for Multi-degraded Image Restoration



Wooksu Shin, Namhyuk Ahn, Jeong-Hyeon Moon, Kyung-Ah Sohn

Ajou University, Korea

Introduction



Overview of DIGNet

Comparison other multi-distortion

Introduction

- Various types of corruption with unknown strength can be applied in real-world applications
- Previous multi-distortion datasets apply distortion to the entire image, or only a single distortion to each region
- We integrate the idea of two multi-distortion regimes
- To effectively restore the multi-degraded image, we propose a distortion information-guided network (DIGNet)

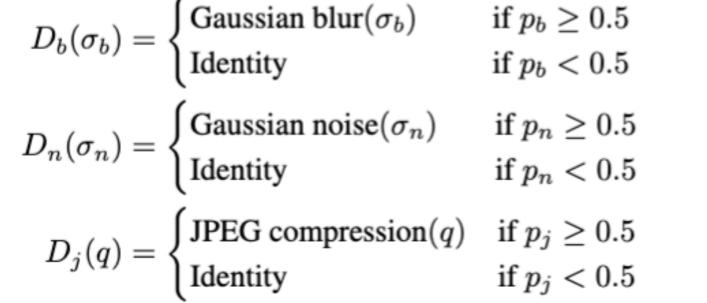
Contribution

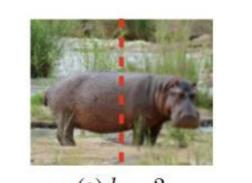
- A holistic multi-distortion dataset (HMDD) jointly implements the sequentially and spatially-applied corruptions
- In DIGNet, we extract conditional distortion information(CDI) that contains useful clues for reconstructing a corrupted image with spatially-variants multi-distortions
- For CDI, we compose two modules; Restoration & Recognition

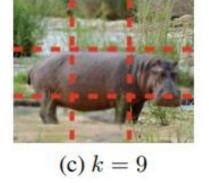
HMDD

Holistic multi-distortion dataset(HMDD)

- Integrate sequential- and spatial- distortion
- Divide random chunks as $I_{gt} \longrightarrow \{I_{gt}^1, \dots, I_{gt}^k\}$
- Then, corrupt by distortions, widely used in image restoration literature, which are randomly selected parameters

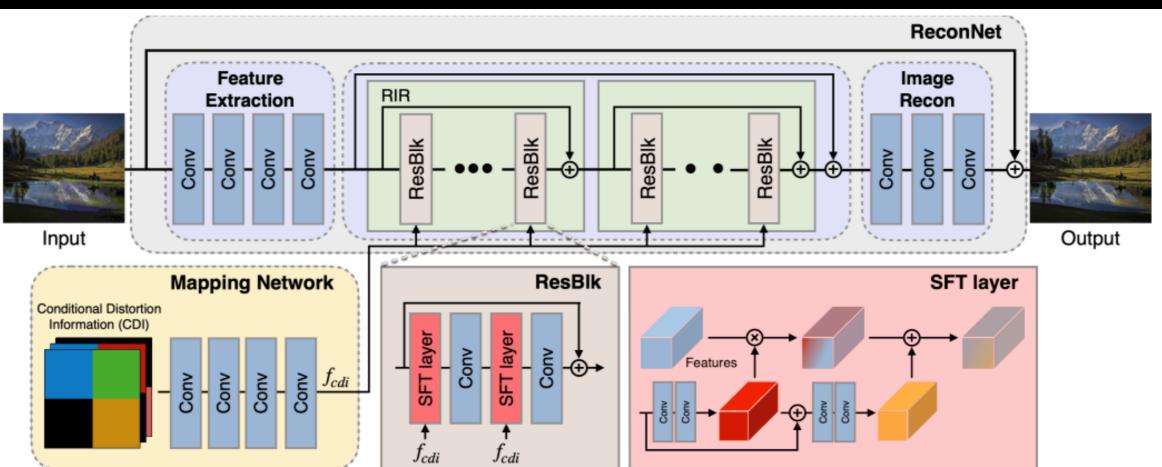






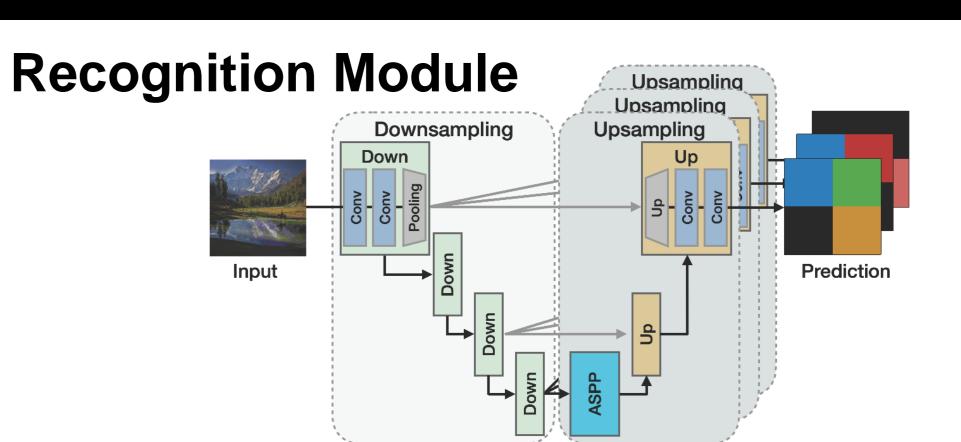
 $I_d^i = D^i(I_{qt}^i); \ D^i = D_i^i \circ D_n^i \circ D_b^i$ $I_d \longleftarrow \{I_d^1, \dots, I_d^k\}.$

Method



Restoration Module

Method



- Train the recognition module in a supervised manner by pixel-MSE
- Distortion-wise decoder outputs the distortionspecific representations

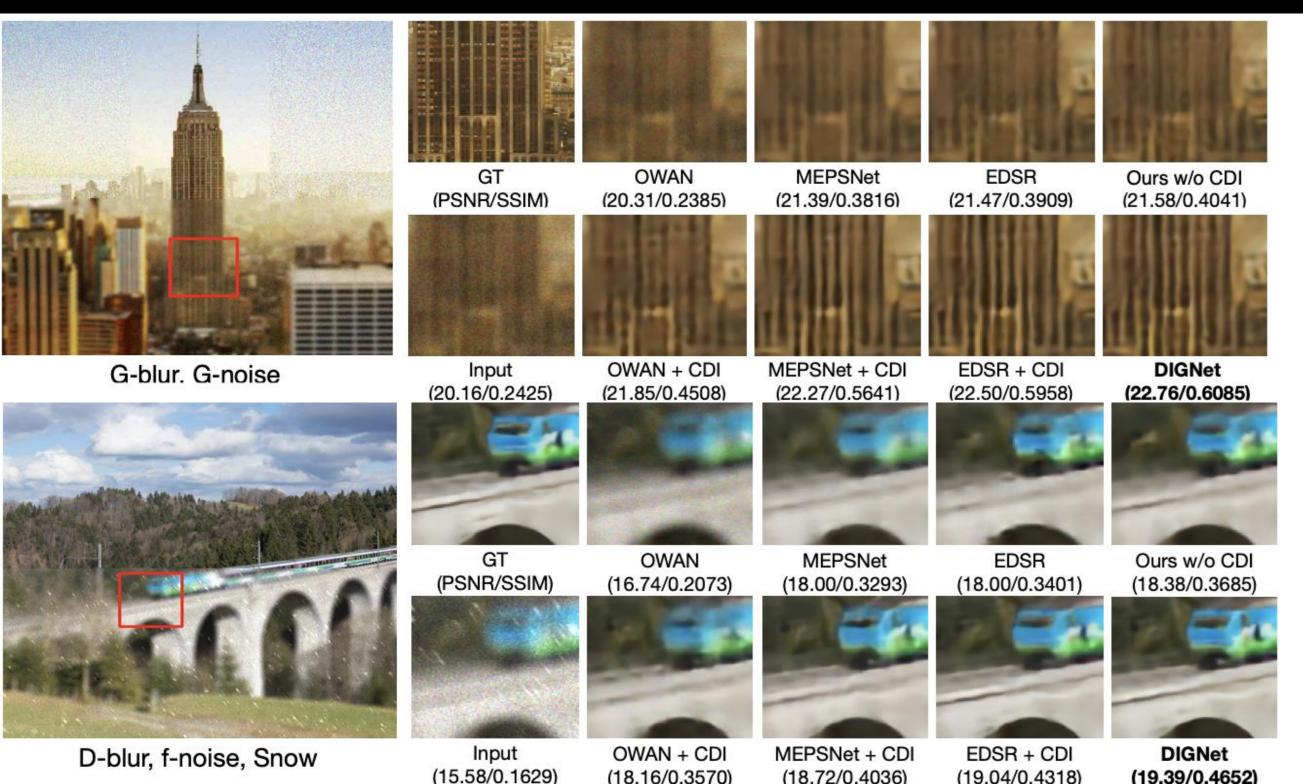
Restoration Module

- Mapping network F_{map} embeds to produce features f_cdi as follows: $f_{cdi} = F_{map}(\widehat{M})$
- Spatial feature transform(SFT) are used to convey the distortion information effectively
- The intermediate feature $f_h \in R^{\{C \times W \times H\}}$ is,

$$(\alpha, \beta) = t(f_{cdi}),$$
 $f_0 = F_e(x)$
 $SFT(f_h; \alpha, \beta) = \alpha \otimes f_h + \beta,$ $f_f = F_f(f_0; \alpha, \beta),$
 $f_o = f_f + f_0,$

• With image reconstruction F_r , final output is, $\hat{y} = F_r(f_o) + x$

Experimental Results



# Down.	# Up.	ASPP	Accuracy (HMDD)				\rightarrow DIGNet	
			G-blur	G-noise	JPEG	Pixel	PSNR	SSIM
2	2		60.76	79.22	87.39	44.59	26.60	0.7559
4	2		71.72	84.26	94.24	60.29	26.68	0.7594
4	2	✓	79.12	87.93	94.01	64.49	26.74	0.7634
4	4	✓	78.77	85.38	93.98	63.01	26.71	0.7628

HMDD-r	Accuracy		
Snow	88.36		
f-noise	97.40		
D-blur	81.89		
Pixel	67.49		

- Quantitative :CDI utilization surpasses the other competitors on both dataset
- Qualitative: Our method produces the restoration capability regardless of the number of distortions and region

	Method	HM.	IDD	HMDD-r	
Michiod		PSNR	SSIM	PSNR	SSIM
	OWAN [32]	23.52	0.5948	22.25	0.5694
	+ CDI	25.96	0.7323	27.13	0.7885
	MEPSNet [21]	25.77	0.7257	26.08	0.7757
	+ CDI	26.60	0.7606	28.43	0.8270
	EDSR [25]	26.25	0.7461	26.70	0.7795
	+ CDI	26.63	0.7622	28.56	0.8401
	Ours w/o CDI	26.52	0.7528	27.91	0.8177
	+ CDI (DIGNet)	26.74	0.7634	28.70	0.8560